

# Overview of ATLAS Muon Spectrometer Alignment

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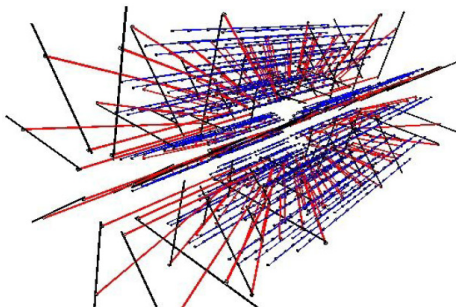
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- 1 Outlook for ATLAS Muon Spectrometer alignment
- 2 Barrel optical alignment
- 3 Endcap optical alignment
- 4 Software for optical alignment
- 5 Track based alignment
- 6 Summary

- momentum measurement design goal:

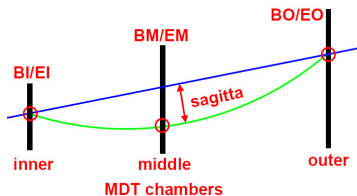
$$\delta p_t / p_t = 10\% \text{ for } 1 \text{ TeV muons} \Rightarrow$$

sagitta of  $500 \mu\text{m}$  measured with  $50 \mu\text{m}$  accuracy

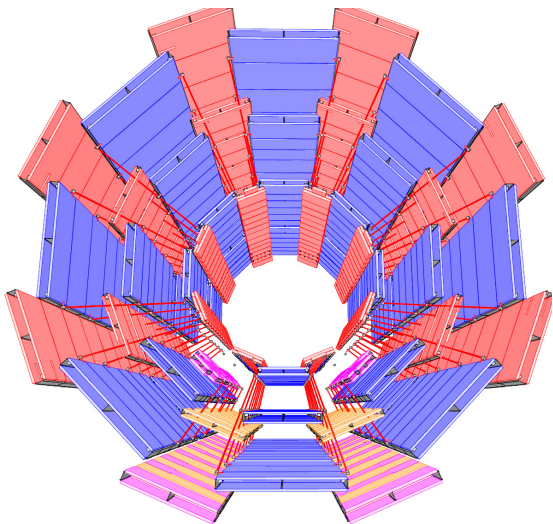
- muon chambers ( $\sim 1200$  in total) are high-precision objects by construction: sense wires are placed with  $20 \mu\text{m}$  precision during chamber assembly

- single muon chamber spatial resolution is  $\sim 40 \mu\text{m}$   
 $\Rightarrow$  muon chambers must be aligned to  $30 \mu\text{m}$  accuracy in order to provide the required momentum resolution

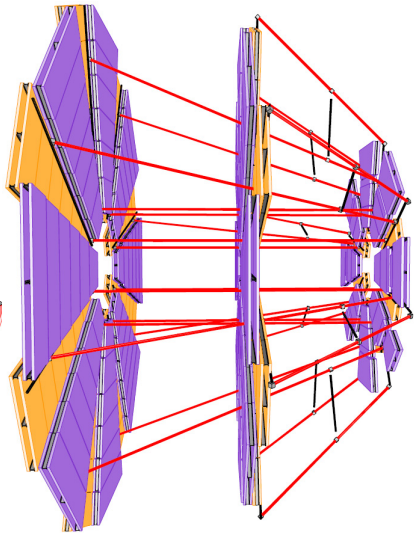
- in the first order, only the relative alignment of triplets of chambers traversed by the same muon track is important
- in the barrel region 3-point straightness monitors (RASNIKS) installed on the inner/middle/outer chambers form such projective lines pointing to the interaction region
- in the endcap regions projective lines are impossible because the cryostats of endcap toroid magnets block the interaction region  $\Rightarrow$  the endcap alignment relies on high precision reference rulers – alignment bars which form alignment grid for the endcaps



# Layout of ATLAS Muon Spectrometer

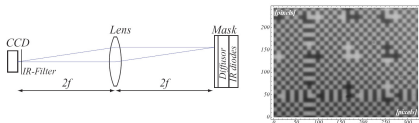


Barrel



Endcap C

# Optical alignment sensors

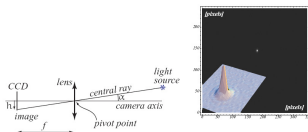
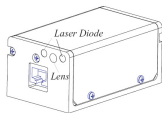
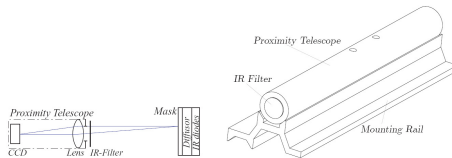


## RASNIK straightness monitor

- 3-point imaging system
- typical accuracy of  $1 \mu\text{m}$  in transverse plane
- operational distance is limited by air turbulence along the optical path (a few meters)
- few tens of  $\mu\text{m}$  accuracy in axial direction

## Proximity monitor

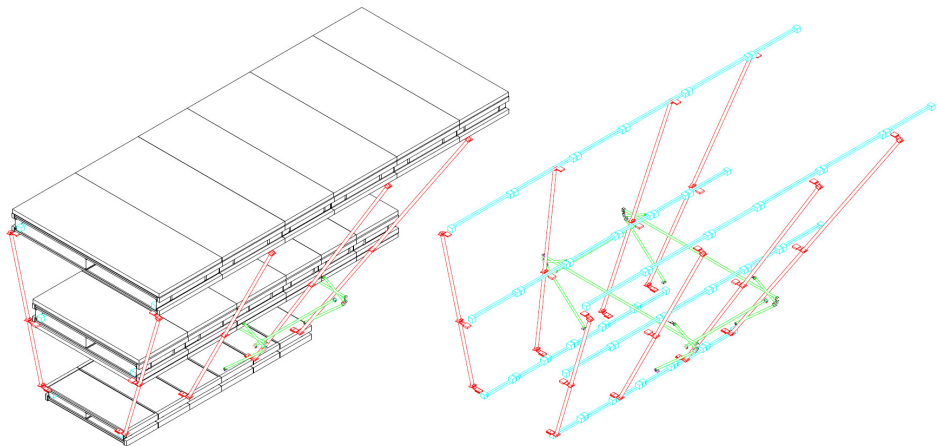
- RASNIK-based – CCD and lens combined into one unit (telescope)
- transverse coordinate accuracy is  $1 \mu\text{m}$
- magnification resolution is  $5 \cdot 10^{-5}$



## BCAM angle monitor

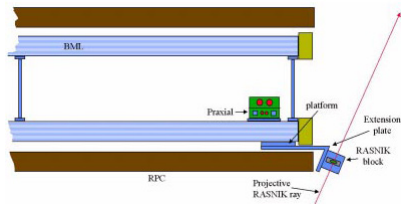
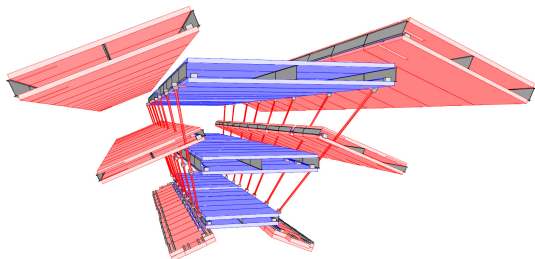
- angular resolution is  $5 \mu\text{rad}$  over dynamic range of  $40 \text{ mrad}$
- needs two light sources to measure axial displacements
- works over any distance without adjusting

# Subsystems of barrel optical alignment



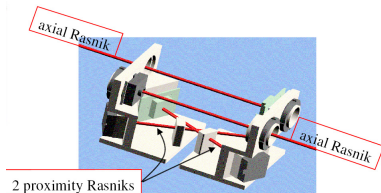
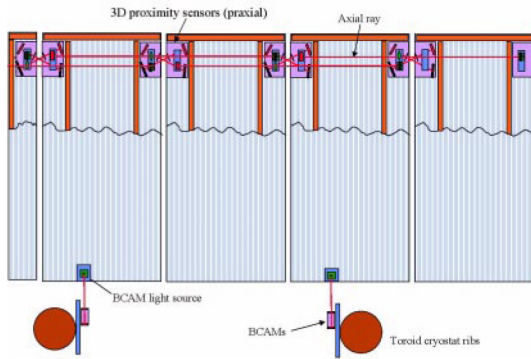
- Projective system (red)
- Axial/Praxial system (cyan)
- Reference system (green)
- Small-to-large chamber connections
- Inplane system (MDT)
- BIL-BIR connections

# Barrel projective system



- provides correction to track sagitta measurement with required  $30\mu\text{m}$  precision
- $2 \times 4$  projective lines per half sector of **large chambers** ( $2 \times 3$  in rail sectors)
- barrel small chambers have to be aligned with respect to large chambers by using muon tracks in the overlap regions
- RASNIK elements are mounted on extension plates which, in turn, are mounted via 3-ball system on platforms precisely glued on tube multilayers

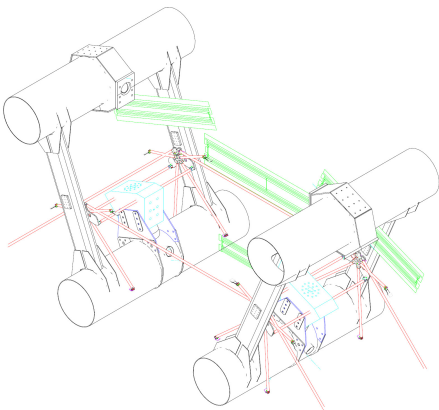
# Barrel axial and praxial systems



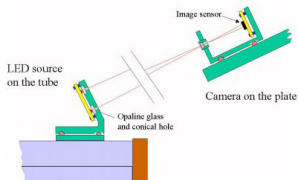
- combines MDT chambers within one sector into a single “rigid” layer which allows to decrease the required number of projective line
- consists of axial and proximity (praxial) subsystems with RASNIK sensors
- axial system measures relative position of the neighboring chamber praxial platform on the far side
- proximity system measures relative position and orientation of two neighboring praxial platforms
- has resolutions better than  $10\ \mu\text{m}$  on translations and  $30\ \mu\text{rad}$  on rotations
- elements of the both subsystems are mounted on the same platform: four praxial platforms are glued at the four corners of all MDT chambers



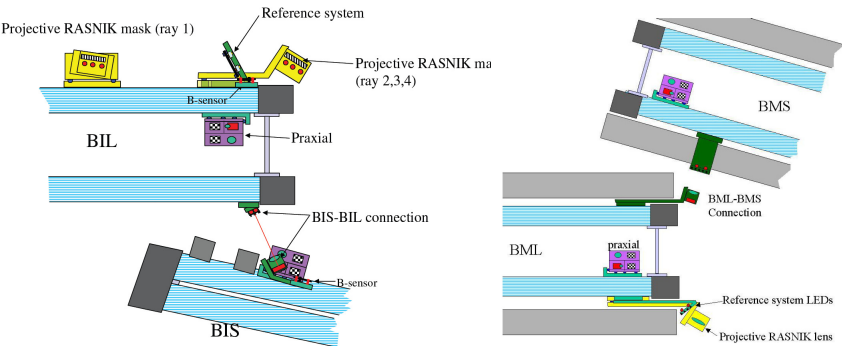
# Barrel reference system



- forms a reference frame for the barrel muon chambers with a precision of  $\sim 400 \mu\text{m}$  on translations and  $\sim 500 \mu\text{rad}$  on rotations
- below 1 mm precision is needed by pattern recognition of muon reconstruction and by magnetic field service
- also allows for second order corrections to sagitta measurements
- plates of the reference system are mounted on the toroid cryostat ribs
- active elements are BCAMs mounted on these plates pointing to LED sources placed on muon chambers or on other plates

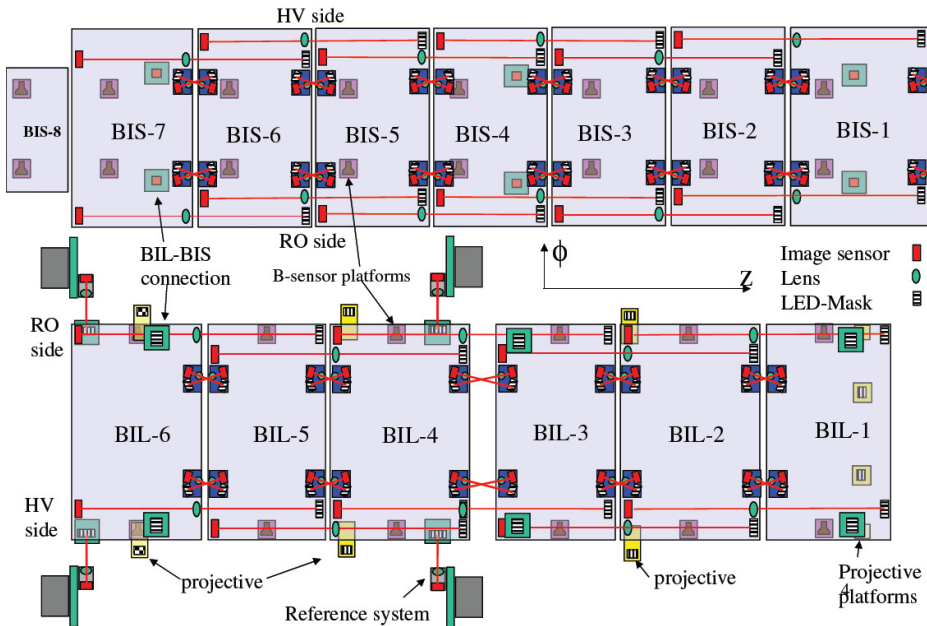


# Barrel small-to-large chamber connections

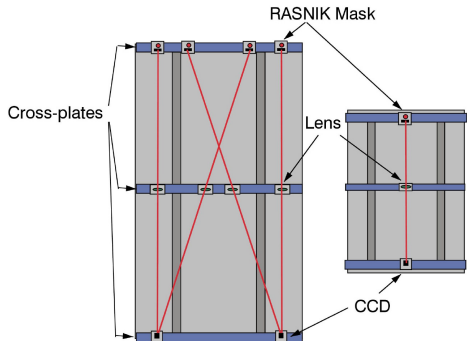


- small-to-large chamber optical connections are part of the reference system
- BCAMs are mounted on large chambers with LED sources placed on adjacent small chambers (reverse setup for inner stations)

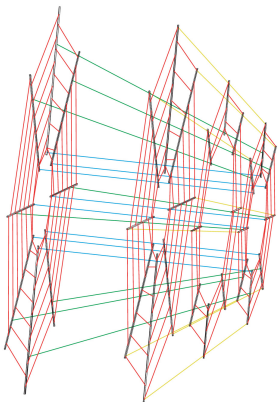
# Overall scheme of barrel optical alignment for a standard sector



- monitors chamber deformations (“M” in MDT) which are described by 8 parameters and result primarily in modification of the wire layout
- based on 4 RASNIK sensors (except BIS chambers which have only 1 sensor)
- calibrated directly during chamber assembly
- determines wire displacements with  $\sim 10 \mu\text{m}$  accuracy



# Layout of endcap optical alignment

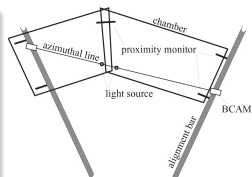


## Endcap reference grid

- alignment bars (black) are instrumented with internal RASNIKS and T-sensors and their shape is determined by calculations
- polar bar-to-bar BCAM lines (green, blue and yellow) form a quasi-projective layout of light rays
- azimuthal bar-to-bar BCAM lines (red) control relative positions of bars within one layer of endcap muon stations

## Endcap chamber-to-bar alignment

- pairs of adjacent small and large chambers form logical units
- two proximity sensors on “bar-sides” of each chamber measure displacements with respect to alignment bars
- connection between a small and a large chamber maintained by one proximity sensor and one azimuthal BCAM pair (needed to control out-of-plane movements in the overlap region)



The bar consists of an aluminum tube:

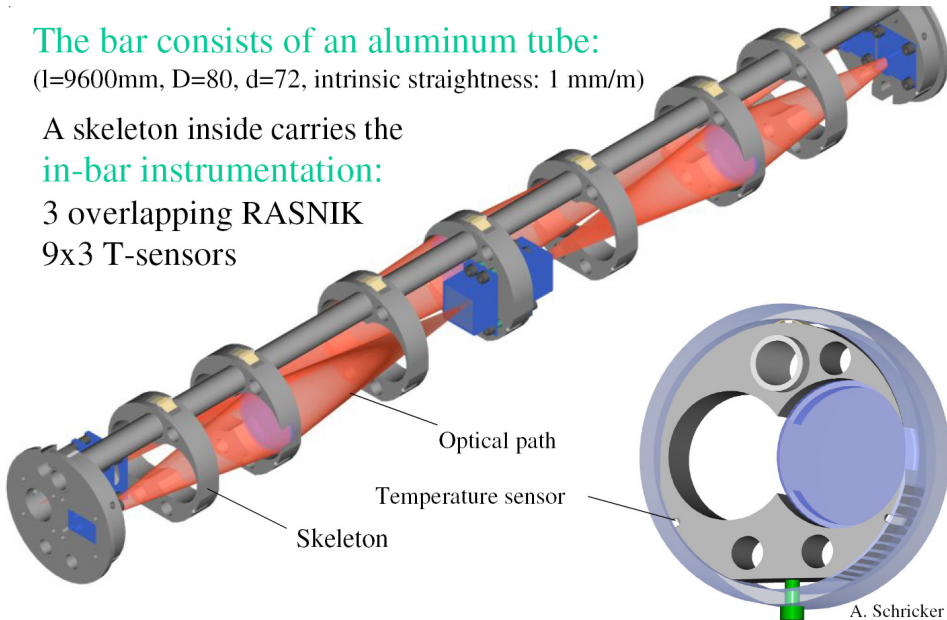
( $l=9600\text{mm}$ ,  $D=80$ ,  $d=72$ , intrinsic straightness:  $1\text{ mm/m}$ )

A skeleton inside carries the

in-bar instrumentation:

3 overlapping RASNIK

9x3 T-sensors



A. Schricker

Two optical alignment reconstruction programs are available:

- **ASAP** (ATLAS Spectrometer Alignment Program) mostly used in barrel
- **ARAMyS** (Alignment Reconstruction for the ATLAS Muon Spectrometer) used in endcaps

## ASAP/ARAMyS inputs

- nominal detector description
- results of geometry survey
- sensor calibration constants
- optical sensors readout (provided by optical alignment DAQ)
- temperature sensors readout (provided by DCS)
- alignment bar shape functions (ARAMyS)

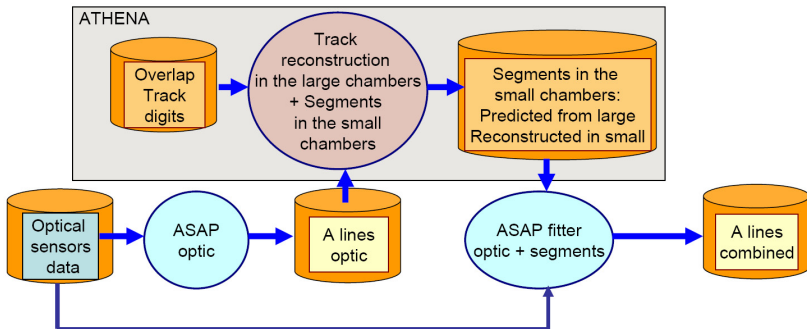
## Reconstruction output

- corrected detector description (ASAP)
- global positions of optical sensors (ARAMyS)

Both programs were intensively used in alignment tests in H8

# Tasks for track based alignment

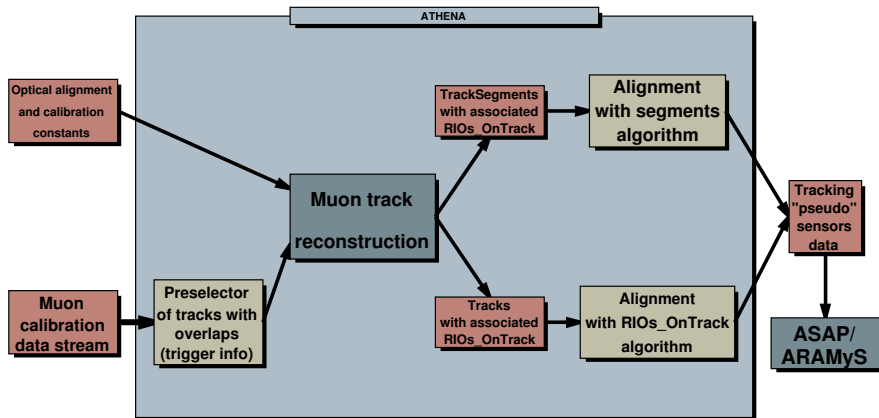
- Many muon chambers don't have projective optical alignment sensors – **no correction to sagitta measurement**
  - ▶ small barrel chambers
  - ▶ BEE chambers
  - ▶ BIS8 chambers
  - ▶ barrel-to-endcap connection
- Tracks passing through overlaps between these chambers and optically aligned chambers must be used to obtain their relative positions





# ATHENA track based alignment package

The package is being developed by MPI MDT group



- based on Common Tracking EDM (uses its data objects and tools) to be independent of particular muon reconstruction algorithm (Muonboy or MOORE)
- have two modes: “alignment with RIO\_OnTrack” which is a universal algorithm and “alignment with segments” which has specific use cases (runs with magnetic field off and “very misaligned detector” scenario at start-up)

## Optical alignment tests

- relative concept
  - ▶ follow variations of sagitta corrections from some moment at which sagitta corrections are known (e.g. straight tracks from special runs with magnetic field switched off)
  - ▶ sensor positioning accuracies and many calibration parameters cancel out
  - ▶ successfully tested in H8 with one octant setup of barrel and endcap chambers with the achieved resolution on sagitta correction of  $10\ \mu\text{m}$  for barrel and  $16\ \mu\text{m}$  for endcap
- absolute concept
  - ▶ provide sagitta corrections at any time without external references
  - ▶ difficult to achieve the required sagitta resolution due to large uncertainties from sensor positioning
  - ▶ tests in H8 gave precision on the order of  $400\ \mu\text{m}$  for absolute chamber positions

## ATLAS muon optical alignment installation (status of 15.05.2006)

- Barrel projective system in sector 13 partly installed, 5 out of 12 alignment rays had clashes with cable trays/cryogenic line/floor bars
- BMS/BMF axial/praxial/inplane system installed and validated
- BOS/BOF/BOG axial/praxial/inplane system installed but some minor realignments needed
- barrel reference system installed and was used during toroid release but not retested since