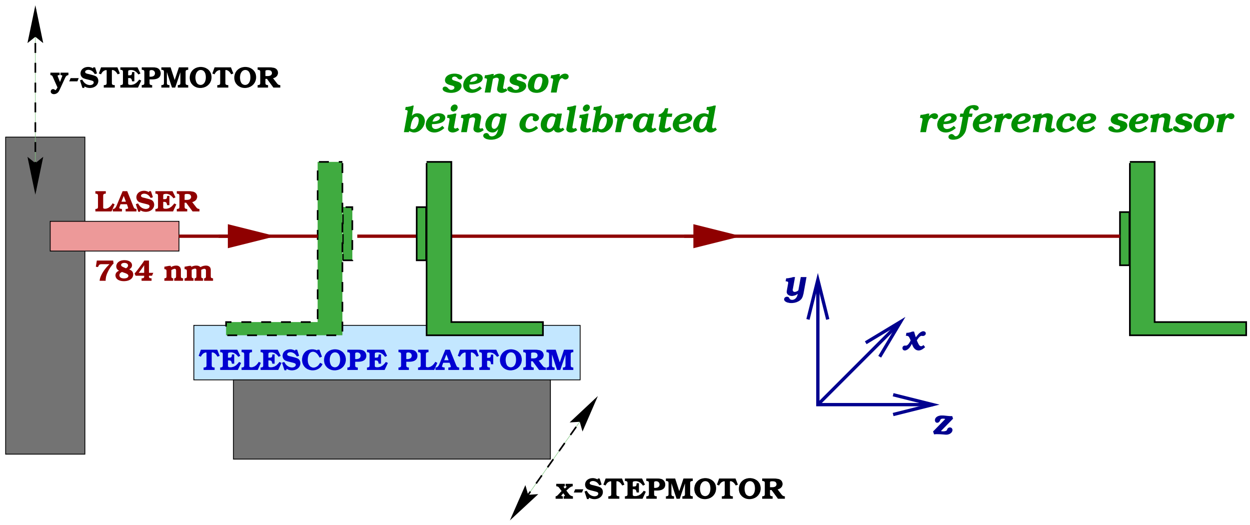
ALMY Sensors

Calibration Procedure

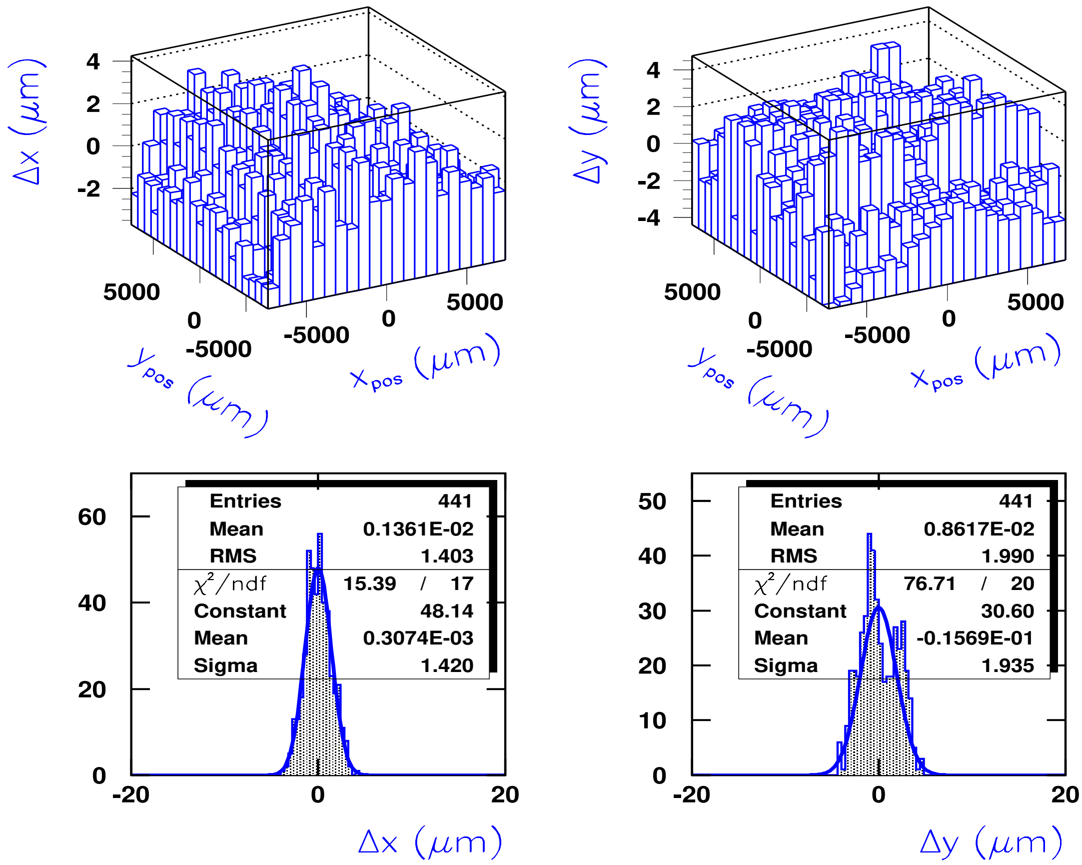


- position resolution
- refraction angle
- displacement measurement
- reflection corrections

Position Resolution

- **better than 2 μm**

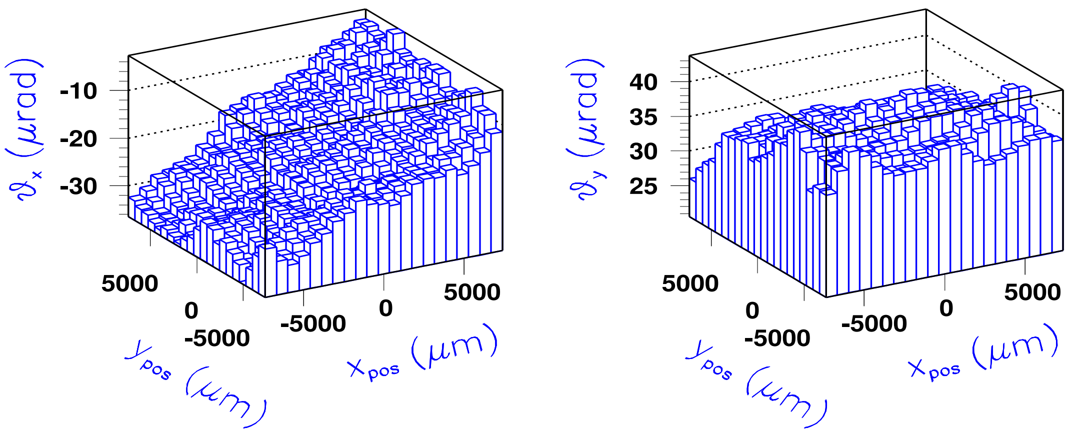
sensor ns036



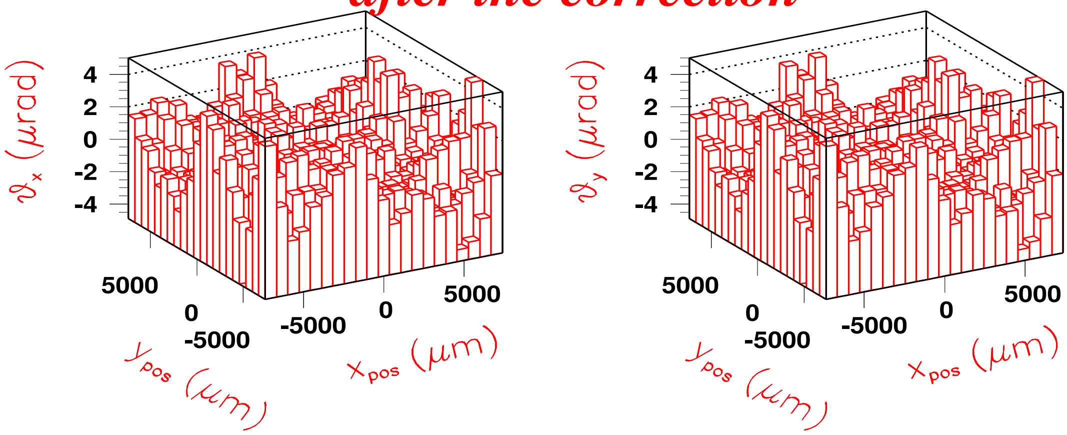
Refraction Angle

- 6-parameter function fit applied for ϑ_x and ϑ_y

sensor ns036



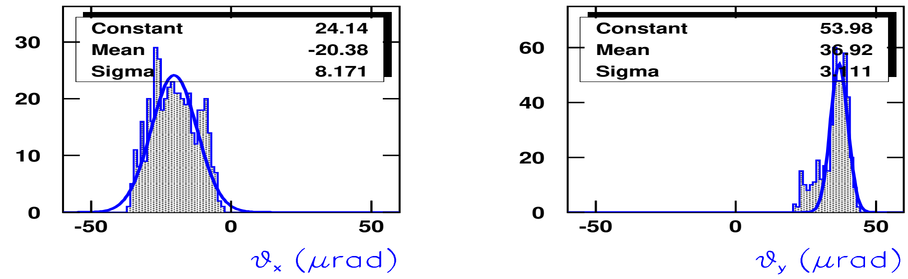
after the correction



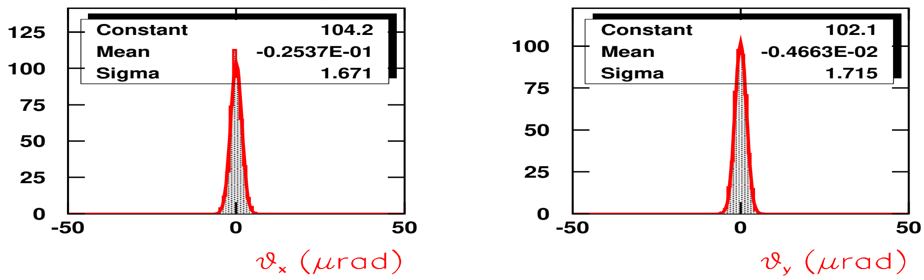
Refraction Angle

sensor	before	correction	after	correction
	$\sigma(\vartheta_x)$ [μrad]	$\sigma(\vartheta_y)$ [μrad]	$\sigma(\vartheta_x)$ [μrad]	$\sigma(\vartheta_y)$ [μrad]
ns031	4.2	10.7	2.4	4.6
ns035	10.2	8.6	2.5	5.1
ns023	6.7	8.5	2.3	2.2
ns036	8.2	3.1	1.7	1.7
ns013	5.5	3.1	2.8	2.5
ns014	2.1	3.8	1.1	1.5
ns016	4.8	8.7	2.2	2.9
ns027	4.9	4.3	4.5	3.3

sensor ns036



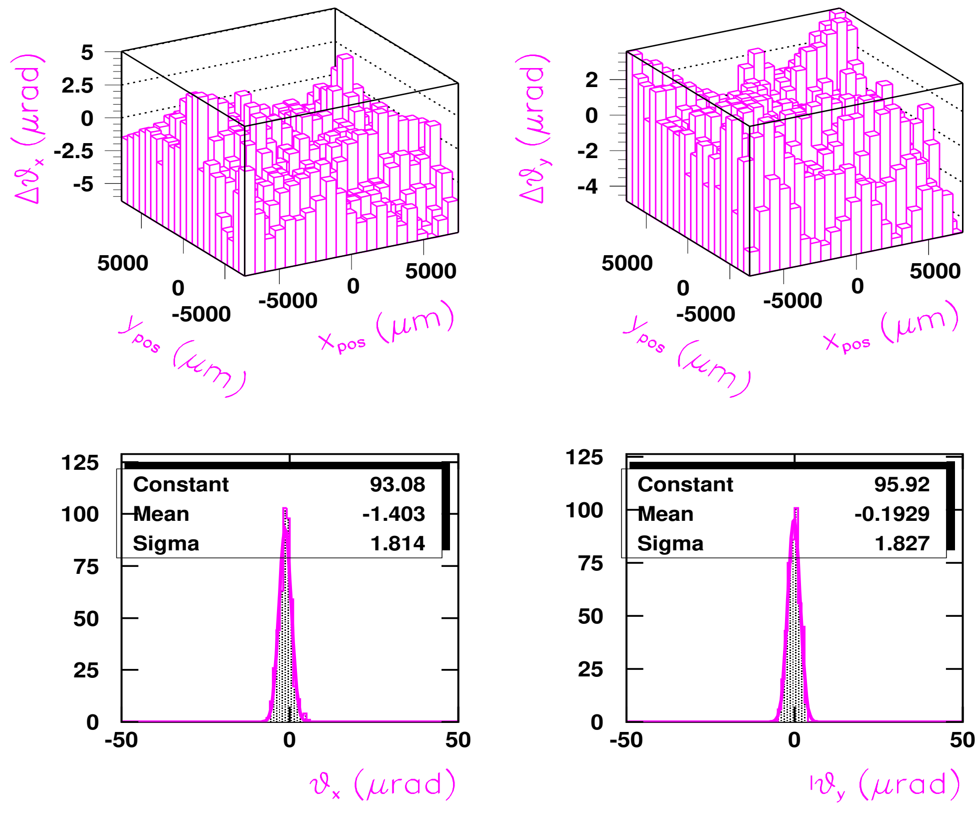
after the correction



- refraction angle determined with precision of 2-3 μrad

Difference in refraction for two sensor orientations

sensor ns036

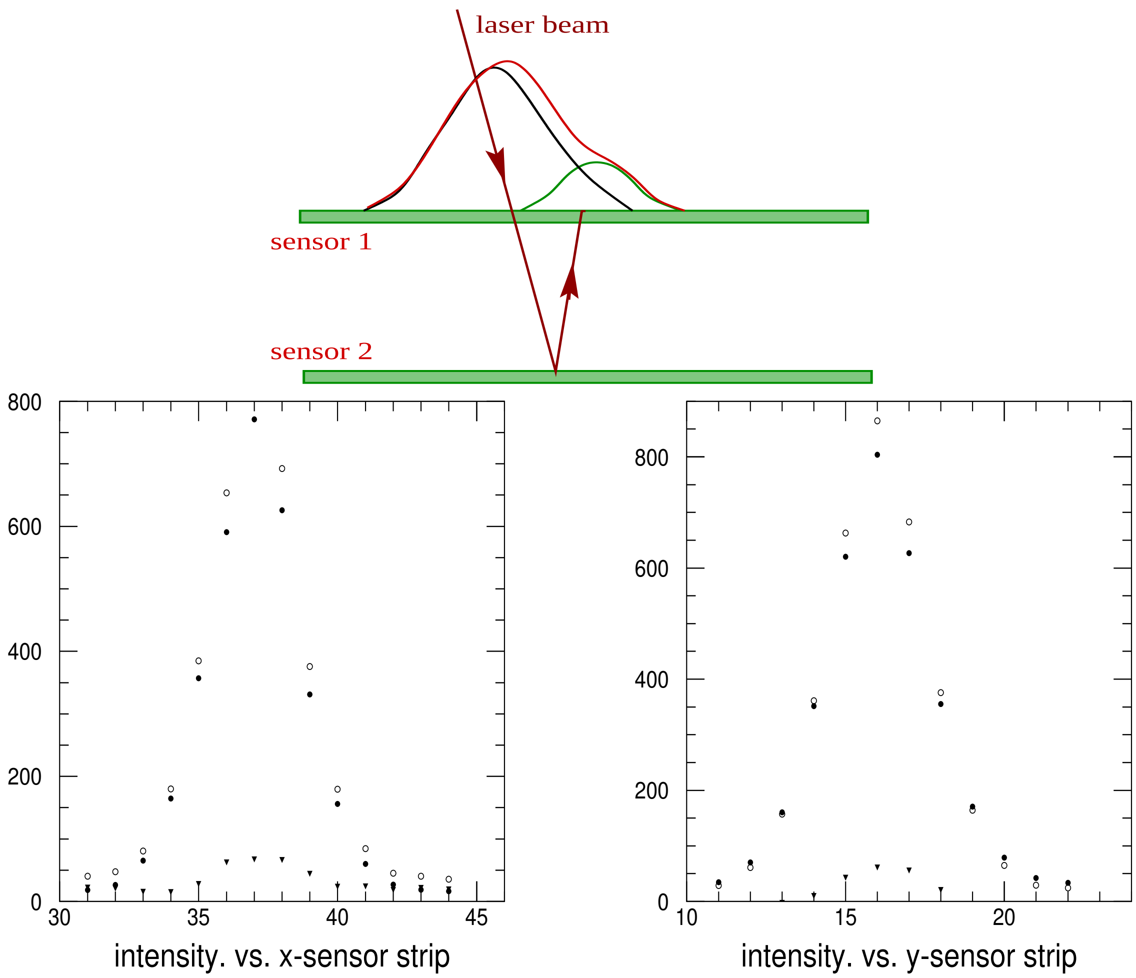


Calibration Parameters

refraction angle: $\vartheta_{x,y} = p1 + p2 \bullet x + p3 \bullet y + p4 \bullet x \bullet y + p5 \bullet x^2 + p6 \bullet y^2$

sensor	ϑ_x							ϑ_y						
	displ.	p1	p2	p3	p4	p5	p6	displ.	p1	p2	p3	p4	p5	p6
ns031	0	-8.79	-0.4e-3	0.5e-3	-0.9e-7	0.4e-7	-0.2e-7	0	27.37	0.5e-3	-0.2e-2	0.8e-7	-0.6e-8	-0.3e-7
ns035	1	-6.55	-0.2e-2	0.6e-3	-0.8e-7	0.5e-7	0.3e-8	-1	-4.26	0.5e-3	-0.2e-2	0.5e-7	-0.2e-7	-0.3e-6
ns023	-9	0.61	-0.1e-2	0.4e-3	-0.2e-8	0.5e-7	-0.1e-7	9	-10.28	0.3e-3	0.2e-2	-0.5e-7	0.7e-8	-0.3e-7
ns036	4	-20.56	-0.2e-2	0.2e-3	-0.6e-7	0.7e-8	-0.9e-7	-13	38.14	0.1e-3	-0.9e-3	0.7e-8	-0.2e-7	-0.1e-6
ns013	10	-15.84	-0.8e-3	-0.2e-3	0.1e-7	0.2e-8	0.4e-8	-20	-24.89	-0.6e-4	-0.4e-3	0.4e-7	0.2e-7	-0.2e-7
ns014	15	5.57	-0.4e-3	-0.2e-3	-0.2e-7	0.2e-7	0.6e-7	-14	3.16	-0.2e-3	-0.8e-3	0.6e-7	0.9e-8	-0.7e-7

Reflection Corrections



• **implemented into the read-out software, applied online**